

WHAT IS CLAIMED IS:

- 1 1. A method for controlling velocity of a model vehicle, the method
2 comprising:
3 providing a control wheel configured to rotate within a range of
4 positions;
5 determining a speed of rotation of the control wheel;
6 correlating the magnitude of power provided to the model vehicle with a
7 speed of rotation of the wheel.
- 1 2. The method of claim 1 wherein correlating the magnitude of power
2 with a speed of rotation comprises multiplying a distance of rotation of the wheel by a
3 factor determined from a time of wheel rotation.
- 1 3. The method of claim 2 wherein the distance of wheel rotation is
2 multiplied by the factor when the speed of wheel rotation exceeds 200 ms/rotation.
- 1 4. The method of claim 2 wherein a value of the factor is proportional
2 to the rotational speed of the wheel.
- 1 5. The method of claim 1 wherein correlating the magnitude of power
2 provided to the model vehicle comprises generating an electrical pulse based upon rotation
3 of the wheel by an increment of angular distance.
- 1 6. The method of claim 5 wherein the electrical pulse is generated by
2 an optical detector receiving light transmitted through a gap of a rotatable disk in
3 mechanical communication with the wheel.
- 1 7. The method of claim 5 wherein the electrical pulse is generated by
2 an optical detector receiving light reflected by a strip located of a rotatable disk in
3 mechanical communication with the wheel.
- 1 8. The method of claim 5 wherein the electrical pulse is generated by a
2 magnetic detector positioned in proximity to a magnetic element of a rotatable disk in
3 mechanical communication with the wheel.

1 9. The method of claim 1 further comprising controlling a polarity of
2 change in the velocity of the model vehicle based upon a phase difference between voltage
3 signals output by optical detectors positioned at different locations along a disk rotational
4 path.

1 10. The method of claim 1 wherein correlating the magnitude of power
2 provided to a model vehicle comprises correlating the magnitude of power provided to a
3 rail of a model train set.

1 11. The method of claim 1 wherein correlating the magnitude of power
2 provided to a model vehicle comprises correlating the magnitude of power provided to a
3 remotely controlled toy selected from the group consisting of a train, a car, and a plane.

1 12. An apparatus for providing power to a model vehicle, the apparatus
2 comprising:
3 a control wheel rotatable over a range of positions;
4 a sensing element in communication with the control wheel and configured
5 to detect a speed of rotation of the wheel; and
6 a processor in electrical communication with the sensing element, the
7 processor configured to correlate wheel rotational speed with a magnitude of power
8 provided from a source to a model vehicle.

1 13. The apparatus of claim 12 wherein the processor is configured to
2 multiply a distance of rotation of the wheel by a factor based upon speed of knob rotation.

1 14. The apparatus of claim 12 wherein the processor is configured to
2 generate the factor proportional to the speed of knob rotation.

1 15. The apparatus of claim 12 wherein the sensing element comprises
2 an optical detector, and the apparatus further comprises:
3 a light source; and
4 a rotatable disk intervening between the light source and the optical
5 detector, the rotatable disk communication with the knob and including gaps spaced at
6 regular angular increments to allow optical communication between the light source and

7 the detector, wherein the processor is configured to detect knob rotation speed based upon
8 a rate of changed transmission of light.

1 16. The apparatus of claim 15 wherein the sensing element further
2 comprises a second optical detector positioned at a different location along a rotational
3 range of the disk, the processor further configured to detect a direction of knob rotation
4 based upon a phase difference between electrical signals produced from the first and
5 second optical detectors.

1 17. The apparatus of claim 12 wherein the sensing element comprises
2 an optical detector, and the apparatus further comprises:
3 a light source; and
4 a rotatable disk intervening between the light source and the optical
5 detector, the rotatable disk communication with the knob and including reflecting
6 elements spaced at regular angular increments to allow optical communication between
7 the light source and the detector, wherein the processor is configured to detect knob
8 rotation speed based upon a rate of changed reflection of light.

1 18. The apparatus of claim 17 wherein the sensing element further
2 comprises a second optical detector positioned at a different location along a rotational
3 range of the disk, the processor further configured to detect a direction of knob rotation
4 based upon a phase difference between signals produced from the first and second optical
5 detectors.

1 19. The apparatus of claim 12 further comprising an antenna configured
2 to allow the processor to communicate with the power source through a wireless signal.

1 20. The apparatus of claim 12 further comprising a wired
2 communication link between the processor and the power source.